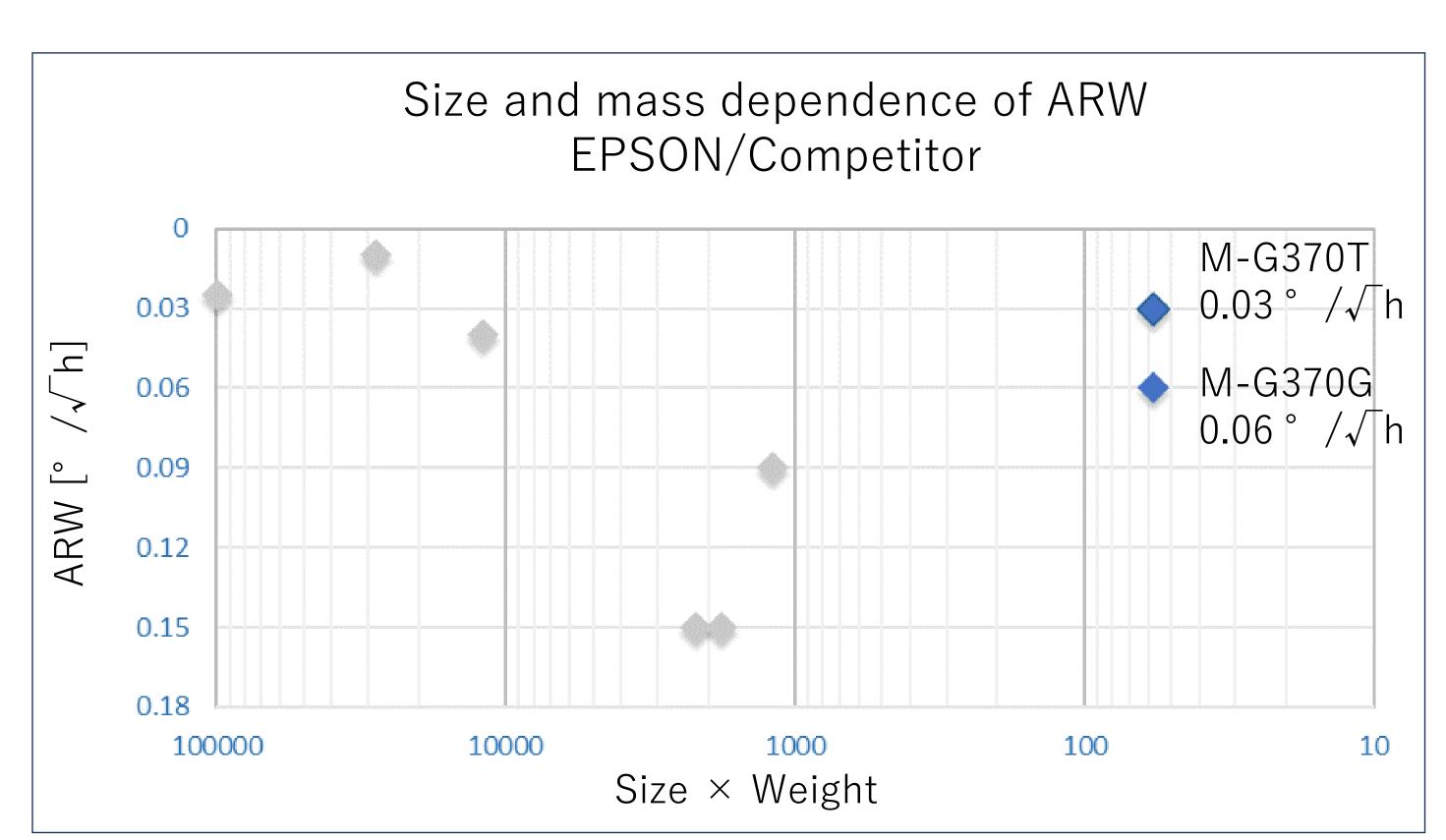


Small, high-precision IMU with excellent SWaP-C [M-G370PDT0]

Attitude detection in space applications such as small satellites





- Attitude detection in space with high-precision gyro and acceleration
- Efficient design with compact size, lightweight and low power consumption.

Radiation test (TID) results

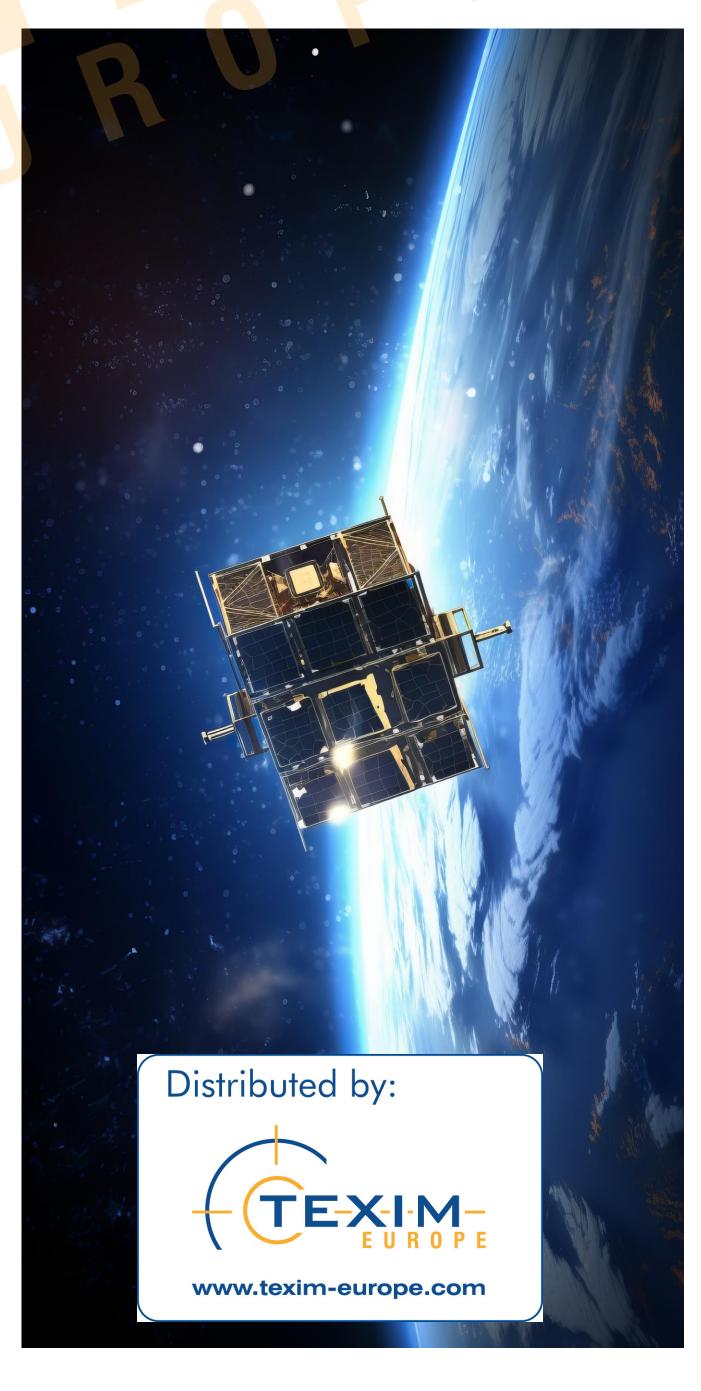
| Functional Test | Total Dose [rad] | 5k | 10k | 20k |
|-----------------|---------------------|--------|--------|--------|
| M-G370PDT0 | Powered | Passed | Passed | Passed |
| | Unpowered | Passed | Passed | Passed |

X Our IMUs are Intended for industrial use.

These results are for reference only and do not guarantee performance in space.

Main Specification of "M-G370PDT0"

| Gyro | | | |
|--|-------------------------------------|--|--|
| Range | ±200°/h | High resolution | |
| ARW | 0.03 ° /√h | Minimal attitude error | |
| • BIS | 0.8°/h | Minimal attitude error | |
| Bandwidth | 189 Hz | Detecting wide vibration | |
| ACCL | | | |
| Range | ±8,16 G (Selectable) | Selectable according to the measurement requirements | |
| • VRW | $0.02 \text{ m/s } \sqrt{\text{h}}$ | Minimal attitude error | |
| Bandwidth | 3 3 3 Hz | Detecting wide vibration | |
| Size | $24 \times 24 \times 10 \text{ mm}$ | Securing design space | |
| Weight | 10 g | Reducing launch costs | |
| Power supply current | 16 mA @3.3 V | Efficient use of power | |



Disclaimer

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Parameters provided in datasheets and / or specifications may vary in different applications and performance may vary over time.

All operating parameters, including typical parameters, must be validated for each customer application by the customer's technical experts.

Please contact us if you have any questions about the contents of the datasheet.

This may not be the latest version of the datasheet. Please check with us if a later version is available.



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